

M29V040

LOW VOLTAGE SINGLE SUPPLY 4 Megabit (512K x 8, Sector Erase) FLASH MEMORY

- FAST ACCESS TIME: 120ns
- 3.3V ± 0.3V SUPPLY VOLTAGE for PROGRAM and ERASE OPERATIONS
- 3.3V ± 0.3V SUPPLY VOLTAGE in READ OPERATIONS
- BYTE PROGRAMMING TIME: 15µs typical
- ERASE TIME
 - Sector: 1.0 sec typical
 - Bulk: 2.5 sec typical
- PROGRAM/ERASE CONTROLLER (P/E.C.)
 - Program Byte-by-Byte
 - Data Polling and Toggle Protocol for P/E.C. Status
- MEMORY ERASE in SECTORS
 - 8 Sectors of 64K Bytes each
 - Sector Protection
 - Multisector Erase
- ERASE SUSPEND and RESUME MODES
- 100,000 PROGRAM/ERASE CYCLES per SECTOR
- LOW POWER CONSUMPTION
 - 25µA typical in Standby current
 - 5mA typical Read Current
 - Automatic CMOS Standby Mode



A0-A18	Address Inputs
DQ0-DQ7	Data Input / Outputs
Ē	Chip Enable
G	Output Enable
W	Write Enable
Vcc	Supply Voltage
V _{SS}	Ground

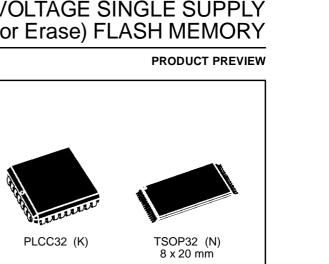
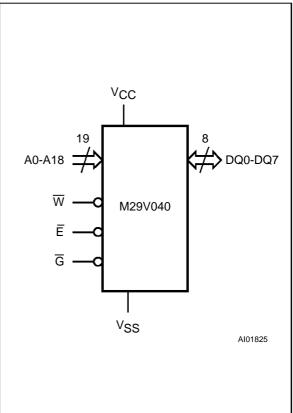


Figure 1. Logic Diagram



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This is preliminary informationon a new product now in development. Details are subject to change without notice.

Figure 2A. LCC Pin Connections

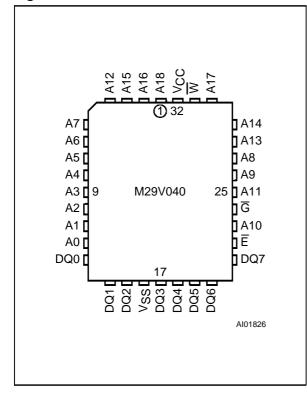
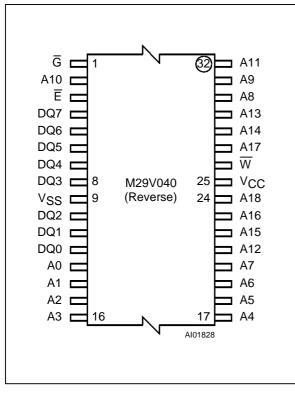
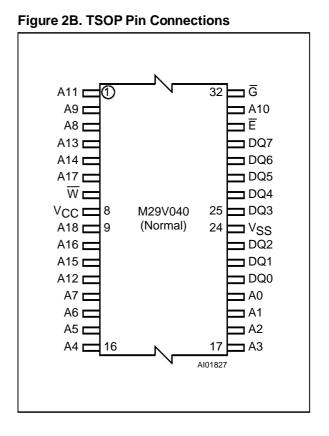


Figure 2C. TSOP Reverse Pin Connections





DESCRIPTION

The M29V040 is a non-volatile memory that may be erased electrically at the sector level, and programmed Byte-by-Byte.

The interface is directly compatible with most microprocessors. PLCC32 and TSOP32 (8 x 20mm) packages are available. Both normal and reverse pin outs are available for the TSOP32 package.

Organisation

The FLASH Memory organisation is 512K x 8 bits with Address lines A0-A18 and Data Inputs/Outputs DQ0-DQ7. Memory control is provided by Chip Enable, Output Enable and Write Enable Inputs.

Erase and Program are performed through the internal Program/Erase Controller (P/E.C.).

Data Outputs bits DQ7 and DQ6 provide polling or toggle signals during Automatic Program or Erase to indicate the Ready/Busy state of the internal Program/Erase Controller.

Sectors

Erasure of the memory is in sectors. There are 8 sectors of 64K bytes each in the memory address space. Erasure of each sector takes typically 1.5 seconds and each sector can be programmed and erased over 100,000 cycles. Each sector may



Symbol	Parameter	Value	Unit
TA	Ambient Operating Temperature	-40 to 85	°C
T _{BIAS}	Temperature Under Bias	-50 to 125	°C
T _{STG}	Storage Temperature	-65 to 150	°C
V _{IO} ⁽²⁾	Input or Output Voltages	–0.6 to 7	V
Vcc	Supply Voltage	-0.6 to 7	V
V _{A9} ⁽²⁾	A9 Voltage	-0.6 to 13.5	V

Table 2. Absolute Maximum Ratings ⁽¹⁾

Notes: 1. Except for the rating "Operating Temperature Range", stresses above those listed in the Table "Absolute Maximum Ratings" may cause permanent damage to the device. These are stress ratings only and operation of the device at these or any other conditions above those indicated in the Operating sections of this specification is not implied. Exposure to Absolute Maximum Rating conditions for extended periods may affect device reliability. Refer also to the SGS-THOMSON SURE Program and other relevant quality documents

2. Minimum Voltage may undershoot to -2V during transition and for less than 20ns.

separately be protected and unprotected against program and erase. Sector erasure may be suspended, while data is read from other blocks of the memory, and then resumed.

Bus Operations

Seven operations can be performed by the appropriate bus cycles, Read Array, Read Electronic Signature, Output Disable, Standby, Protect Sector, Unprotect Sector, and Write the Command of an Instruction.

Command Interface

Command Bytes can be written to a Command Interface (C.I.) latch to perform Reading (from the Array or Electronic Signature), Erasure or Programming. For added data protection, command execution starts after 4 or 6 command cycles. The first, second, fourth and fifth cycles are used to input a code sequence to the Command Interface (C.I.). This sequence is equal for all P/E.C. instructions. Command itself and its confirmation - if it applies - are given on the third and fourth or sixth cycles.

Instructions

Seven instructions are defined to perform Reset, Read Electronic Signature, Auto Program, Sector Auto Erase, Auto Bulk Erase, Sector Erase Suspend and Sector Erase Resume. The internal Program/Erase Controller (P/E.C.) handles all timing and verification of the Program and Erase instructions and provides Data Polling, Toggle, and Status data to indicate completion of Program and Erase Operations.

Instructions are composed of up to six cycles. The first two cycles input a code sequence to the Command Interface which is common to all P/E.C. instructions (see Table 7 for Command Descriptions). The third cycle inputs the instruction set up command instruction to the Command Interface. Subsequent cycles output Signature, Sector protection or the addressed data for Read operations. For added data protection, the instructions for program and sector or bulk erase require further command inputs. For a Program instruction, the fourth command cycle inputs the address and data to be programmed. For an Erase instruction (sector or bulk), the fourth and fifth cycles input a further code sequence before the Erase confirm command on the sixth cycle. Byte programming takes typically 15µs while erase is performed in typically 2.0 seconds.

Erasure of a memory sector may be suspended, in order to read data from another sector, and then resumed. Data Polling, Toggle and Error data may be read at any time, including during the programming or erase cycles, to monitor the progress of the operation. When power is first applied or if V_{CC} falls below V_{LKO} , the command interface is reset to Read Array.



Table 3. Operations

Operation	Ē	G	w	DQ0 - DQ7
Read	V _{IL}	V _{IL}	V _{IH}	Data Output
Write	VIL	ViH	VIL	Data Input
Output Disable	VIL	V _{IH}	V _{IH}	Hi-Z
Standby	V _{IH}	Х	Х	Hi-Z

Note: $X = V_{IL} \text{ or } V_{IH}$

Table 4. Electronic Signature

Code	Ē	G	w	A0	A1	A6	A9 Other Addresses DQ0 -		DQ0 - DQ7
Manufact. Code	VIL	VIL	VIH	VIL	VIL	VIL	V _{ID}	Don't Care	20h
Device Code	VIL	VIL	Vih	Vih	VIL	VIL	VID	Don't Care	0E3h

Table 5. Sector Protection Status

Code	Ē	G	w	A0	A1	A6	A16	A17	A18	Other Addresses	DQ0 - DQ7
Protected Sector	VIL	VIL	VIH	VIL	VIH	VIL	SA	SA	SA	Don't Care	01h
Unprotected Sector	VIL	VIL	VIH	VIL	VIH	VIL	SA	SA	SA	Don't Care	00h

Note: SA = Address of sector being checked

DEVICE OPERATION

Signal Descriptions

A0-A18 Address Inputs. The address inputs for the memory array are latched during a write operation. The A9 address input is used also for the Electronic Signature read and Sector Protect verification. When A9 is raised to V_{ID} , either a Read Manufacturer Code, Read Device Code or Verify Sector Protection is enabled depending on the combination of levels on A0, A1 and A6. When A0, A1 and A6 are Low, the Electronic Signature Manufacturer code is read, when A0 is High and A1 and A6 are Low, the Device code is read, and when A1 is High and A0 and A6 are low, the Sector Protection Status is read for the sector addressed by A16, A17, A18.

DQ0-DQ7 Data Input/Outputs. The data input is a byte to be programmed or a command written to

the C.I. Both are latched when Chip Enable \overline{E} and Write Enable \overline{W} are active. The data output is from the memory Array, the Electronic Signature, the Data Polling bit (DQ7), the Toggle Bit (DQ6), the Error bit (DQ5) or the Erase Timer bit (DQ3). Ouputs are valid when Chip Enable \overline{E} and Output Enable \overline{G} are active. The output is high impedance when the chip is deselected or the outputs are disabled.

 $\overline{\mathbf{E}}$ Chip Enable. The Chip Enable activates the memory control logic, input buffers, decoders and sense amplifiers. $\overline{\mathbf{E}}$ High deselects the memory and reduces the power consumption to the standby level. $\overline{\mathbf{E}}$ can also be used to control writing to the command register and to the memory array, while $\overline{\mathbf{W}}$ remains at a low level. Addresses are then latched on the falling edge of $\overline{\mathbf{E}}$ while data is latched on the rising edge of $\overline{\mathbf{E}}$. The Chip Enable must be forced to V_{ID} during Sector Unprotect operations.



Table 6. Instructions (1)

Mne.	Instr.	Cyc.		1st Cyc.	2nd Cyc.	3rd Cyc.	4th Cyc.	5th Cyc.	6th Cyc.	7th Cyc.		
RST ^(3,9)	Reset	1+	Addr. (2,6)	х	Read Men	Read Memory Array (until a now write avale is initiated				
	Reset		Data	0F0h		Read Memory Array until a new write cycle is initiated.						
RSIG (3)	Read Electronic	3+	Addr. (2,6)	x5555h	x2AAAh	x5555h		ctronic Sigr				
KSIG	Signature	5+	Data	0AAh	55h	90h	write cycle is initiated. See Note 4.			e 4.		
RSP ⁽³⁾	Read Sector	3+	Addr. (2,6)	x5555h	x2AAAh	x5555h		tor Protecti		ew write		
	Protection	5+	Data	0AAh	55h	90h	cycle is in	le is initiated. See Note 5.				
PG	Program	4	Addr. ^(2,6)	x5555h	x2AAAh	x5555h	Program Address		Read Data Polling or Toggle			
			Data	0AAh	55h	0A0h	Program Data	Bit until Program completes.				
SE	Sector Erase	6	Addr. ^(2,6)	x5555h	x2AAAh	x5555h	x5555h	x2AAAh	Sector Address	Additional Sector ⁽⁷⁾		
			Data	0AAh	55h	80h	0AAh	55h	30h	30h		
BE	Bulk Erase	6	Addr. (2,6)	x5555h	x2AAAh	x5555h	x5555h	x2AAAh	x5555h	Note 8		
	Duik Liuoo	Ū	Data	0AAh	55h	80h	0AAh	55h	10h	11010 0		
ES	Erase	1	Addr. (2,6)	х		Read until Toggle stops, then read all the data needed fro			d from any			
	Suspend		Data	0B0h	sector(s) not being erased then Resume Erase.							
ER	Erase	1	Addr. (2,6)	х				until Erase	completes	or Erase		
	Resume		Data	30h	is suspend	ded anothe	r time					

Notes: 1. Command not interpreted in this table will default to read array mode.

2. X = Don't Care.
 3. The first cycle of the RST, RSP or RSIG instruction is followed by read operations to read memory array, Status Register or

Series of the first cycle of the rest, Ror of Noro interfeed on the followed by fead operations to fead methods and y, Batter Register of the first cycle of the rest cycle of the

status.

6. Address bits A16, A17, A18 are don't care for coded address inputs.

7. Optional, additional sectors addresses must be entered within a 80 µs delay after last write entry, timeout status can be verified through DQ3 value. When full command is entered, read Data Polling or Toggle bit until Erase is completed or suspended.

8. Read Data Polling or Toggle bit until Erase completes.
 9. A wait time of 5μs is necessary after a Reset command, before starting any operation.



DEVICE OPERATION (cont'd)

 $\overline{\mathbf{G}}$ **Output Enable.** The Output Enable gates the outputs through the data buffers during a read operation. $\overline{\mathbf{G}}$ must be forced to V_{ID} level during Sector Protect and Sector Unprotect operations.

 $\overline{\mathbf{W}}$ Write Enable. This input controls writing to the Command Register and Address and Data latches. Addresses are latched on the falling edge of $\overline{\mathbf{W}}$, and Data Inputs are latched on the rising edge of $\overline{\mathbf{W}}$.

V_{CC} Supply Voltage. The power supply for all operations (Read, Program and Erase).

 V_{SS} Ground. V_{SS} is the reference for all voltage measurements.

Table 7. Commands

Hex Code	Command
00h	Invalid/Reserved
10h	Bulk Erase Confirm
30h	Sector Erase Resume/Confirm
80h	Set-up Erase
90h	Read Electronic Signature/ Sector protection Status
0A0h	Program
0B0h	Erase Suspend
0F0h	Reset

Table 8. Status Register

DQ	Name	Logic Level	Definition	Note
		·1'	Erase Complete	
7	Data	,0,	Erase on Going	Indicates the P/E.C. status, check during Program or Erase, and on completion
	Polling	DQ	Program Complete	before checking bits DQ5 for Program or Erase Success.
		DQ	Program on Going	
		'-1-0-1-0-1-'	Erase or Program on Going	Successive read output complementary
6	Toggle Bit	'-0-0-0-0-0-0-'	Program ('0' on DQ6) Complete	data on DQ6 while Programming or Erase operations are going on. DQ6 remain at constant level when P/E.C. operations are
		'-1-1-1-1-1-1-'	Erase or Program ('1' on DQ6) Complete	completed or Erase Suspend is acknowledged.
5	Error Bit	'1'	Program or Erase Error	This bit is set to '1' if P/E.C. has exceded
		'0'	Program or Erase on Going	the specified time limits.
4		'1'		
		'0'		
	Erase	'1'	Erase Timeout Period Expired	P/E.C. Erase operation has started. Only
3	Time Bit	,0,	Erase Timeout Period on Going	possible command entry is Erase Suspend (ES). An additional sector to be erased in parallel can be entered to the P/E.C.
2	Reserved			
1	Reserved			
0	Reserved			

Notes: Logic level '1' is High, '0' is Low. -0-1-0-0-1-1-1-0- represent bit value in successive Read operations.



Memory Sectors

The memory sectors of the M29V040 are shown in Figure 5. The memory array is divided in 8 sectors of 64K bytes. Each sector can be erased separately or any combination of sectors can be erased simultaneously. The Sector Erase operation is managed automatically by the P/E.C. The operation can be suspended in order to read from any another sector, and then resumed.

Sector Protection provides additional data security. Each sector can be separately protected or unprotected against Program or Erase. Bringing A9 and \overline{G} to V_{ID} initiates protection, while bringing A9, \overline{G} and \overline{E} to V_{ID} cancels the protection. The sector affected during protection is addressed by the inputs on A16, A17, and A18. Unprotect operation affects all sectors.

Operations

Operations are defined as specific bus cycles and signals which allow Memory Read, Command Write, Output Disable, Standby, Read Status Bits, Sector Protect/Unprotect, Sector Protection Check and Electronic Signature Read. They are shown in Tables 3, 4, 5.

Read. Read operations are used to output the contents of the Memory Array, the Status Register or the Electronic Signature. Both Chip Enable \overline{E} and Output Enable \overline{G} must be low in order to read the output of the memory. The Chip Enable input also provides power control and should be used for device selection. Output Enable should be used to gate data onto the output independent of the device selection. The data read depends on the previous command written to the memory (see instructions RST and RSIG, and Status Bits).

Write. Write operations are used to give Instruction Commands to the memory or to latch input data to be programmed. A write operation is initiated when Chip Enable \overline{E} is Low and Write Enable \overline{W} is Low with Output Enable \overline{G} High. Addresses are latched on the falling edge of \overline{W} or \overline{E} whichever occurs last. Commands and Input Data are latched on the rising edge of \overline{W} or \overline{E} whichever occurs first.

Output Disable. The data outputs are high impedance when the Output Enable \overline{G} is High with Write Enable \overline{W} High.

Standby. The memory is in standby when Chip Enable E is High and Program/Erase Controller P./E.C. is Idle. The power consumption is reduced to the standby level and the outputs are high impedance, independent of the Output Enable \overline{G} or Write Enable W inputs.

Automatic Standby. After 150ns of inactivity and when CMOS levels are driving the addresses, the chip automatically enters a pseudo standby mode

where consumption is reduced to the CMOS standby value, while outputs are still driving the bus.

Electronic Signature. Two codes identifying the manufacturer and the device can be read from the memory, the manufacturer's code for SGS-THOM-SON is 20h, and the device code is E3h for the M29V040. These codes allow programming equipment or applications to automatically match their interface to the characteristics of the particular manufacturer's product. The Electronic Signature is output by a Read operation when the voltage applied to A9 is at V_{ID} and address inputs A1 and A6 are at Low. The manufacturer code is output when the Address input A0 is Low and the device code when this input is High. Other Address inputs are ignored. The codes are output on DQ0-DQ7. This is shown in Table 4.

The Electronic Signature can also be read, without raising A9 to V_{ID} by giving the memory the instruction RSIG (see below).

Sector Protection. Each sector can be separately protected against Program or Erase. Sector Protection provides additional data security, as it disables all program or erase operations. This mode is activated when both A9 and \overline{G} are set to V_{ID} and the sector address is applied on A16, A17 and A18. Sector protection is programmed using a Presto F program like algorithm. Protection is initiated on the edge of \overline{W} falling to V_{IL}. Then after a delay of 100 μ s, the edge of \overline{W} rising to V_{IH} ends the protection operation. Protection verify is achieved by bringing \vec{G} , \vec{E} and A6 to V_{IL} while \vec{W} is at V_{IH} and A9 at V_{ID}. Under these conditions, reading the data output will yield 01h if the sector defined by the inputs on A16, A17 and A18 is protected. Any attempt to program or erase a protected sector will be ignored by the device.

Any protected sector can be unprotected to allow updating of bit contents. All sectors must be protected before an unprotect operation. Sector unprotect is activated when A9, \overline{G} and \overline{E} are at V_{ID}. The addresses inputs A6, A16, A12 must be maintained at VIH. Sector unprotect is performed through a Presto F Erase like algorithm. Unprotect is initiated by the edge of W falling to VIL. After a delay of 10ms, the edge of \overline{W} rising to V_{IH} will end the unprotection operation. Unprotect verify is achieved by bringing \overline{G} and \overline{E} to V_{IL} while A6 and \overline{W} are at V_{IH} and A9 at V_{ID}. In these conditions, reading the output data will yield 00h if the sector defined by the inputs on A16, A17 and A18 has been successfully unprotected. All combinations of A16, A17 and A18 must be addressed in order to ensure that all of the 8 sectors have been unprotected. Sector Protection Status is shown in Table 5



Table 9. AC Measurement Cond	litions
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	SRAM Interface Levels	EPROM Interface Levels		
Input Rise and Fall Times	≤ 10ns	≤ 10ns		
Input Pulse Voltages	0 to 3V	0.45V to 2.4V		
Input and Output Timing Ref. Voltages	1.5V	0.8V and 2V		

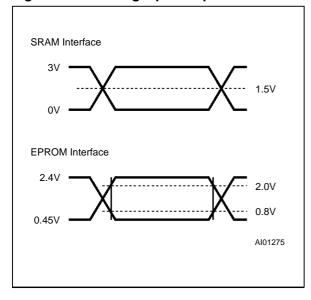


Figure 3. AC Testing Input Output Waveform

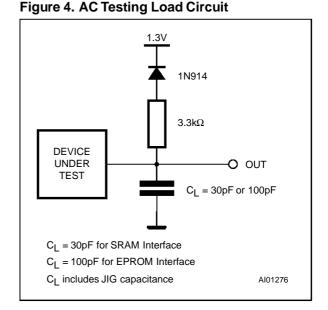


Table 10. Capacitance⁽¹⁾ ($T_A = 25 \text{ °C}, f = 1 \text{ MHz}$)

Symbol	Parameter	Test Condition	Min	Max	Unit
CIN	Input Capacitance	$V_{IN} = 0V$		6	pF
Соит	Output Capacitance	$V_{OUT} = 0V$		12	pF

Note: 1. Sampled only, not 100% tested.

Instructions and Commands

The Command Interface (C.I.) latches commands written to the memory. Instructions are made up from one or more commands to perform Reset, Read Electronic Signature, Sector Erase, Bulk Erase, Program, Sector Erase Suspend and Erase Resume. Commands are made of address and data sequences. Addresses are latched on the falling edge of \overline{W} or \overline{E} and data is latched on the falling edge of \overline{W} or \overline{E} and data is latched on the rising of \overline{W} or \overline{E} . The instructions require from 1 to 6 cycles, the first or first three of which are always write operations used to initiate the command. They are followed by either further write cycles to confirm the first command or execute the command immediately. Command sequencing must be followed exactly. Any invalid combination of com-

mands will reset the device to Read Array. The increased number of cycles has been chosen to assure maximum data security. Commands are initialised by two preceding coded cycles which unlock the Command Interface. In addition, for Erase, command confirmation is again preceeded by the two coded cycles.

P/E.C. status is indicated during command execution by Data Polling on DQ7, detection of Toggle on DQ6, or Error on DQ5 and Erase Timer DQ3 bits. Any read attempt during Program or Erase command execution will automatically output those four bits. The P/E.C. automatically sets bits DQ3, DQ5, DQ6 and DQ7. Other bits (DQ0, DQ1, DQ2 and DQ4) are reserved for future use and should be masked.





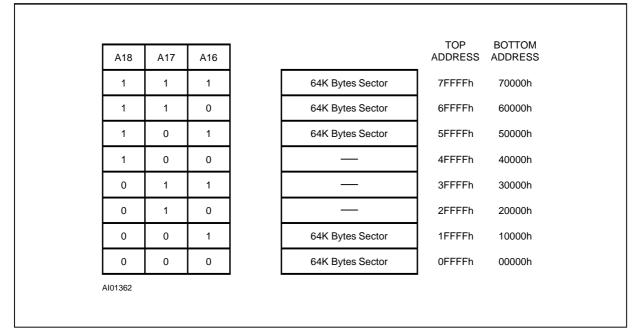


Figure 5. Memory Map and Sector Address Table

Table 11. DC Characteristics

 $(T_A = 0 \text{ to } 70^{\circ}\text{C}, -20 \text{ to } 85^{\circ}\text{C} \text{ or } -40 \text{ to } 85^{\circ}\text{C}; V_{CC} = 3.3\text{V} \pm 0.3\text{V})$

Symbol	Parameter	Test Condition	Min	Мах	Unit
Iц	Input Leakage Current	$0V \leq V_{IN} \leq V_{CC}$		±1	μΑ
ILO	Output Leakage Current	$0V \le V_{OUT} \le V_{CC}$		±1	μA
I _{CC1}	Supply Current (Read) TTL	$\overline{E} = V_{IL}, \overline{G} = V_{IH}, f = 6MHz$		20	mA
I _{CC2}	Supply Current (Standby) TTL	Ē = V _{IH}		0.2	mA
I _{CC3}	Supply Current (Standby) CMOS	$\overline{E} = V_{CC} \pm 0.2V$		50	μA
I _{CC4}	Supply Current (Program or Erase)	Byte program, Sector or Bulk Erase in progress		30	mA
V _{IL}	Input Low Voltage		0.7 V _{CC}	0.8	V
VIH	Input High Voltage		2	V _{CC} + 0.5	V
Vol	Output Low Voltage	I _{OL} = 2mA		0.45	V
	Output High Voltage TTL	I _{OH} = -2mA	2.4		V
Voh	Output High Voltage CMOS	I _{OH} = –100µА	V _{CC} –0.4		V
		I _{OH} = -2mA	0.85 x V _{CC}		V
V _{ID}	A9 Voltage (Electronic Signature)		11.5	12.5	V
I _{ID}	A9 Current (Electronic Signature)	A9 = V _{ID}		50	μA
V _{LKO}	Supply Voltage (Erase and Program lock-out)		1.9	2.2	V



Table 12. Read AC Characteristics

 $(T_A = 0 \text{ to } 70^{\circ}\text{C}, -20 \text{ to } 85^{\circ}\text{C} \text{ or } -40 \text{ to } 85^{\circ}\text{C}; V_{CC} = 3.3\text{V}\pm0.3\text{V})$

	Alt	Parameter	Test Condition			M29	V040				
Symbol				-120 -150			-200		Unit		
Gymbol				SRAM Interface		SRAM Interface		EPROM Interface			
				Min	Max	Min	Max	Min	Max		
t _{AVAV}	t _{RC}	Address Valid to Next Address Valid	$\overline{E} = V_{IL}, \overline{G} = V_{IL}$	120		150		200		ns	
t _{AVQV}	tACC	Address Valid to Output Valid	$\overline{E}=V_{IL},\overline{G}=V_{IL}$		120		150		200	ns	
t _{ELQX} ⁽¹⁾	t∟z	Chip Enable Low to Output Transition	$\overline{G} = V_{IL}$	0		0		0		ns	
t _{ELQV} ⁽²⁾	t _{CE}	Chip Enable Low to Output Valid	$\overline{G} = V_{IL}$		120		150		200	ns	
tglax ⁽¹⁾	to∟z	Output Enable Low to Output Transition	$\overline{E} = VIL$	0		0		0		ns	
t _{GLQV} ⁽²⁾	toe	Output Enable Low to Output Valid	$\overline{E} = V_{IL}$		50		55		70	ns	
t _{EHQX}	t _{OH}	Chip Enable High to Output Transition	$\overline{G} = V_{IL}$	0		0		0		ns	
t _{EHQZ} ⁽¹⁾	t _{HZ}	Chip Enable High to Output Hi-Z	$\overline{G} = V_{IL}$		30		40		50	ns	
t _{GHQX}	t _{OH}	Output Enable High to Output Transition	$\overline{E} = V_{IL}$	0		0		0		ns	
t _{GHQZ} ⁽¹⁾	tDF	Output Enable High to Output Hi-Z	Ē = VIL		30		40		50	ns	
t _{AXQX}	t _{OH}	Address Transition to Output Transition	$\overline{E} = V_{IL}, \overline{G} = V_{IL}$	0		0		0		ns	

Notes: 1. Sampled only, not 100% tested. 2. G may be delayed by up to t_{ELQV} - t_{GLQV} after the falling edge of E without increasing t_{ELQV}.

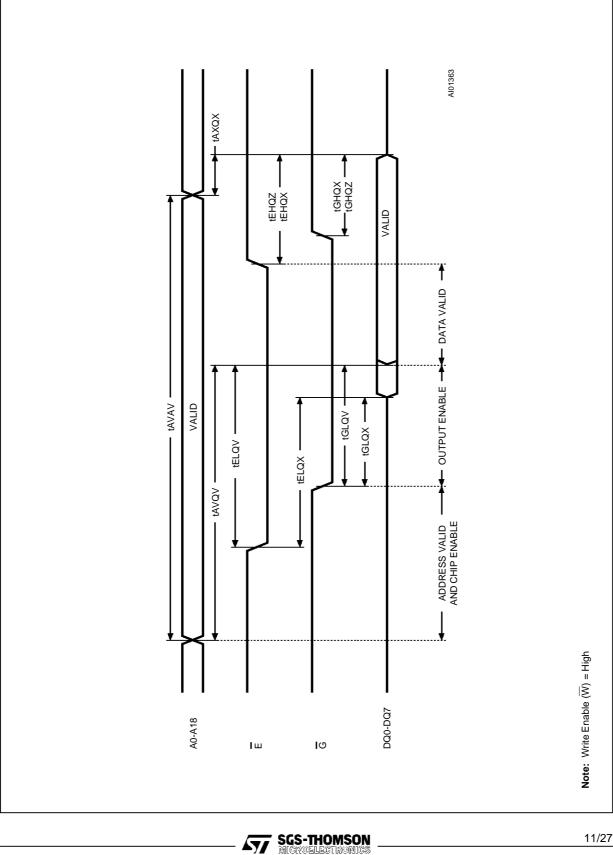
Data Polling Bit DQ7. When Programming operations are in progress, this bit outputs the complement of the bit being programmed on DQ7. During Erase operation, it outputs a '0'. After completion of the operation, DQ7 will output the bit last programmed or a '1' after erasing. Data Polling is valid only effective during P/E.C. operation, that is after the fourth \overline{W} pulse for programming or after the sixth \overline{W} pulse for Erase. It must be performed at the

address being programmed or at an address within the sector being erased. If the byte to be programmed belongs to a protected sector the com-mand is ignored. If all the sectors selected for erasure are protected, DQ7 will set to '0' for about 100µs, and then return to previous addressed memory data. See Figure 9 for the Data Polling flowchart and Figure 10 for the Data Polling waveforms.



SGS-THOMSON





	Alt	It Parameter		M29V040					
Symbol		Falameter	-120 -150			-200		Unit	
Cymbol			SRAM Interface		SRAM Interface		EPROM Interface		
			Min	Мах	Min	Мах	Min	Max	
t _{AVAV}	twc	Address Valid to Next Address Valid	120		150		200		ns
t _{ELWL}	tcs	Chip Enable Low to Write Enable Low	0		0		0		ns
t _{WLWH}	t _{WP}	Write Enable Low to Write Enable High	50		65		80		ns
tovwн	tDS	Input Valid to Write Enable High	50		65		80		ns
t _{WHDX}	t _{DH}	Write Enable High to Input Transition	0		0		0		ns
t _{WHEH}	t _{CH}	Write Enable High to Chip Enable High	0		0		0		ns
t _{WHWL}	t _{WPH}	Write Enable High to Write Enable Low	30		35		35		ns
tavwl	tas	Address Valid to Write Enable Low	0		0		0		ns
t _{WLAX}	t _{AH}	Write Enable Low to Address Transition	50		65		65		ns
t _{GHWL}		Output Enable High to Write Enable Low	0		0		0		ns
t VCHEL	t _{VCS}	V _{CC} High to Chip Enable Low	50		50		50		μs
t _{WHQV1} ⁽¹⁾		Write Enable High to Output Valid (Program)	15		15		15		μs
twhqv2 ⁽¹⁾		Write Enable High to Output Valid (Sector Erase)	2.0	30	2.0	30	2.0	30	sec
t _{WHGL}	t _{OEH}	Write Enable High to Output Enable Low	0		0		0		ns

Table 13. Write AC Characteristics, Write Enable Controlled

 $(T_A = 0 \text{ to } 70^{\circ}C, -20 \text{ to } 85^{\circ}C \text{ or } -40 \text{ to } 85^{\circ}C; V_{CC} = 3.3V \pm 0.3V)$

Note: 1. Time is measured to Data Polling or Toggle Bit, $t_{WHQV} = t_{WHQ7V} + t_{Q7VQV}$

Toggle Bit DQ6. When Programming operations are in progress, successive attempts to read DQ6 will output complementary data. DQ6 will toggle following toggling of either \overline{G} or \overline{E} when \overline{G} is low. The operation is completed when two successive reads yield the same output data. The next read will output the bit last programmed or a '1' after erasing. The toggle bit is valid only effective during

P/E.C. operations, that is after the fourth \overline{W} pulse for programming or after the sixth \overline{W} pulse for Erase. If the byte to be programmed belongs to a protected sector the command will be ignored. If the sectors selected for erasure are protected, DQ6 will toggle for about 100µs and then return back to Read. See Figure 11 for Toggle Bit flowchart and Figure 12 for Toggle Bit waveforms.





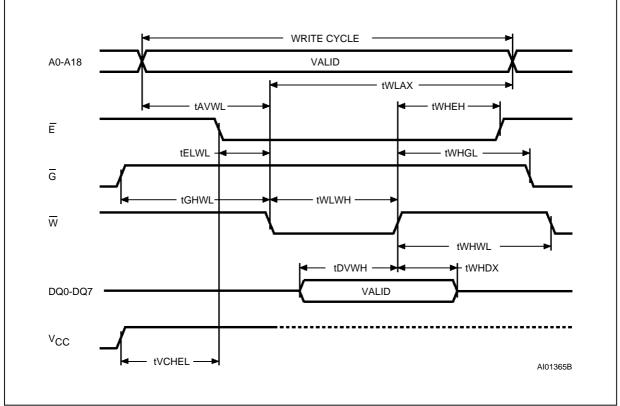


Figure 7. Write AC Waveforms, W Controlled

Note: Address are latched on the falling edge of \overline{W} , Data is latched on the rising edge of \overline{W} .

Error bit DQ5. This bit is set to '1' by the P/E.C when there is a failure of byte programming, sector erase, or bulk erase that results in invalid data being programmed in the memory sector. In case of error in sector erase or byte program, the sector in which the error occured or to which the programmed byte belongs, must be discarded. Other sectors may still be used. Error bit resets after Reset (RST) instruction. In case of success, the error bit will set to '0' during Program or Erase and to valid data after write operation is completed.

Erase Timer bit DQ3. This bit is set to '0' by the P/E.C. when the last sector Erase command has been entered to the Command Interface and it is awaiting the Erase start. When the wait period is finished, after 80 to $120\mu s$, DQ3 returns back to '1'.

Coded Cycles. The two coded cycles unlock the Command Interface. They are followed by a command input or a comand confirmation. The coded cycles consist of writing the data 0AAh at address 5555h during the first cycle and data 55h at address 2AAAh during the second cycle. Addresses are

latched on the falling edge of \overline{W} or \overline{E} while data is latched on the rising edge of \overline{W} or \overline{E} . The coded cycles happen on first and second cycles of the command write or on the fourth and fifth cycles.

Reset (RST) instruction. The Reset instruction consists of one write operation giving the command 0F0h. It can be optionally preceded by the two coded cycles. After wait state of 5μ s, subsequent read operations will read the memory array addressed and output the read byte.

Read Electronic Signature (RSIG) instruction. This instruction uses the two coded cycles followed by one write cycle giving the command 90h to address 5555h for command setup. A subsequent read will output the manufacturer code, the device code or the sector protection status depending on the levels of A0, A1, A6, A16, A17 and A18. The manufacturer code, 20h, is output when the addresses lines A0, A1 and A6 are Low, the device code, 0E2h is output when A0 is High with A1 and A6 Low.



	Alt	Parameter	M29V040						
Symbol	All	Faranieler	-120 -150			-200		Unit	
Symbol			SRAM Interface		SRAM Interface		EPROM Interface		
			Min	Max	Min	Max	Min	Max	
t _{AVAV}	twc	Address Valid to Next Address Valid	120		150		200		ns
twlel	tws	Write Enable Low to Chip Enable Low	0		0		0		ns
t _{ELEH}	tCP	Chip Enable Low to Chip Enable High	50		65		80		ns
t _{DVEH}	t _{DS}	Input Valid to Chip Enable High	50		65		80		ns
t _{EHDX}	t _{DH}	Chip Enable High to Input Transition	0		0		0		ns
tenwn	t _{WH}	Chip Enable High to Write Enable High	0		0		0		ns
t _{EHEL}	t _{СРН}	Chip Enable High to Chip Enable Low	30		35		35		ns
t _{AVEL}	tas	Address Valid to Chip Enable Low	0		0		0		ns
t _{ELAX}	t _{AH}	Chip Enable Low to Address Transition	50		65		65		ns
t _{GHEL}		Output Enable High Chip Enable Low	0		0		0		ns
t∨CHWL	tvcs	V _{CC} High to Write Enable Low	50		50		50		ns
t _{EHQV1} ⁽¹⁾		Chip Enable High to Output Valid (Program)	15		15		15		μs
t _{EHQV2} ⁽¹⁾		Chip Enable High to Output Valid (Sector Erase)	2.0	30	2.0	30	2.0	30	sec
t _{EHGL}	tоен	Chip Enable High to Output Enable Low	0		0		0		ns

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Table 14. Write AC Characteristics, Chip Enable Controlled

 $(T_A = 0 \text{ to } 70^{\circ}\text{C}, -20 \text{ to } 85^{\circ}\text{C} \text{ or } -40 \text{ to } 85^{\circ}\text{C}; V_{CC} = 3.3\text{V}\pm0.3\text{V})$

Note: 1. Time is measured to Data Polling or Toggle Bit, $t_{WHQV} = t_{WHQ7V} + t_{Q7VQV}$

Read Sector Protection. The use of Read Electronic Signature (RSIG) command also allows access to the sector protection status verify. After giving the RSIG command, A0 and A6 are set to V_{IL} with A1 at V_{IH}, while A16, A17 and A18 define the sector of the sector to be verified. A read in these conditions will output a 01h if sector is protected and a 00h if sector is not protected.

Bulk Erase (BE) instruction. This instruction uses six write cycles. The Erase Set-up command 80h is written to address 5555h on third cycle after the two coded cycles. The Bulk Erase Confirm command 10h is written at address 5555h on sixth cycle after another two coded cycles. If the second command given is not an erase confirm or if the coded cycles are wrong, the instruction aborts and the

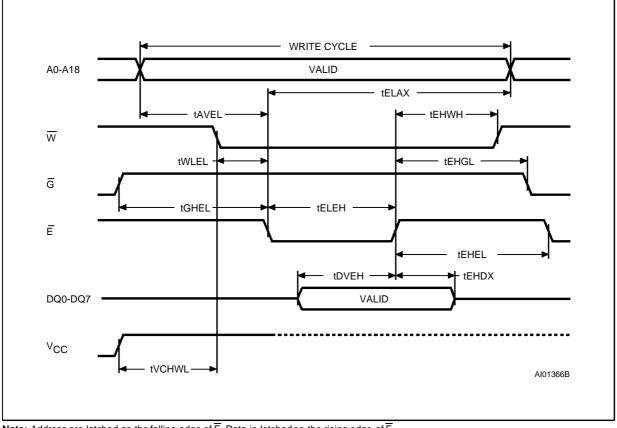


Figure 8. Write AC Waveforms, **E** Controlled

Note: Address are latched on the falling edge of \overline{E} , Data is latched on the rising edge of \overline{E} .

device is reset to Read Array. It is not necessary to program the array with 00h first as the P/E.C. will automatically do this before erasing to 0FFh. Read operations after the sixth rising edge of \overline{W} or \overline{E} output the status register bits. During the execution of the erase by the P/E.C. the memory accepts only the Reset (RST) command. Read of Data Polling bit DQ7 returns '0', then '1' on completion. The Toggle Bit DQ6 toggles during erase operation and stops when erase is completed. After completion the Status Register bit DQ5 returns '1' if there has been an Erase Failure because the erasure has not been verified even after the maximum number of erase cycles have been executed.

Sector Erase (SE) instruction. This instruction uses a minimum of six write cycles. The Erase Set-up command 80h is written to address 5555h on third cycle after the two coded cycles. The Sector Erase Confirm command 30h is written on sixth cycle after another two coded cycles. During the input of the second command an address within the sector to be erased is given and latched into the memory. Additional Sector Erase confirm commands and sector addresses can be written subsequently to erase other sectors in parallel, without further coded cycles. The erase will start after an Erase timeout period of about 100µs. Thus, additional Sector Erase commands must be given within this delay. The input of a new Sector Erase command will restart the timeout period. The status of the internal timer can be monitored through the level of DQ3, if DQ3 is '0' the Sector Erase Command has been given and the timeout is running, if DQ3 is '1', the timeout has expired and the P/E.C is erasing the sector(s). Before and during Erase timeout, any command different from 30h will abort the instruction and reset the device to read array mode. It is not necessary to program the sector with 00h as the P/E.C. will do this automatically before to erasing to 0FFh. Read operations after the sixth rising edge of \overline{W} or \overline{E} output the status register status bits.

During the execution of the erase by the P/E.C., the memory accepts only the ES (Erase Suspend) and



	Alt	Parameter	M29V040						
Symbol			-120 -150			-200		Unit	
Cymbol			SRAM Interface		SRAM Interface		EPROM Interface		
			Min	Max	Min	Max	Min	Max	
twhq7v1 ⁽²⁾		Write Enable Hi <u>gh</u> to DQ7 Valid (Program, W Controlled)	10		10		10		ms
t _{WHQ7V2} ⁽²⁾		Write Enable High to <u>D</u> Q7 Valid (Sector Erase, W Controlled)	1.5	30	1.5	30	1.5	30	sec
t _{EHQ7V1} ⁽²⁾		Chip Enable Hig <u>h</u> to DQ7 Valid (Program, E Controlled)	10		10		10		ms
t _{EHQ7V2} ⁽²⁾		Chip Enable High to <u>D</u> Q7 Valid (Sector Erase, E Controlled)	1.5	30	1.5	30	1.5	30	sec
tq7vqv		Q7 Valid to Output Valid (Data Polling)		50		55		70	ns
t _{WHQV1}		Write Enable High to Output Valid (Program)	10		10		10		μs
t _{WHQV2}		Write Enable High to Output Valid (Sector Erase)	1.5	30	1.5	30	1.5	30	sec
t _{EHQV1}		Chip Enable High to Output Valid (Program)	10		10		10		μs
t _{EHQV2}		Chip Enable High to Output Valid (Sector Erase)	1.5	30	1.5	30	1.5	30	sec

Table 15. Data Polling and Toggle Bit AC Characteristics⁽¹⁾

 $(T_A = 0 \text{ to } 70^{\circ}\text{C}, -20 \text{ to } 85^{\circ}\text{C} \text{ or } -40 \text{ to } 85^{\circ}\text{C}; V_{CC} = 3.3\text{V}\pm0.3\text{V})$

Notes: 1. All other timings are defined in Read AC Characteristics table. 2. twHQ7V is the Program or Erase time.

DEVICE OPERATION (cont'd)

RST (Reset) instructions. Data Polling bit DQ7 returns '0' while the erasure is in progress and '1' when it has completed. The Toggle Bit DQ6 toggles during the erase operation. It stops when erase is completed. After completion the Status Register bit DQ5 returns '1' if there has been an Erase Failure because erasure has not completed even after the maximum number of erase cycles have been executed. In this case, it will be necessary to input a Reset (RST) to the command interface in order to reset the P/E.C. **Program (PG) instruction.** This instruction uses four write cycles. The Program command A0h is written on the third cycle after two coded cycles. A fourth write operation latches the Address on the falling edge of \overline{W} or \overline{E} and the Data to be written on its rising edge and starts the P/E.C. During the execution of the program by the P/E.C., the memory will not accept any instruction. Read operations output the status bits after the programming has started. Memory programming is made only by writing '0' in place of '1' in a Byte.



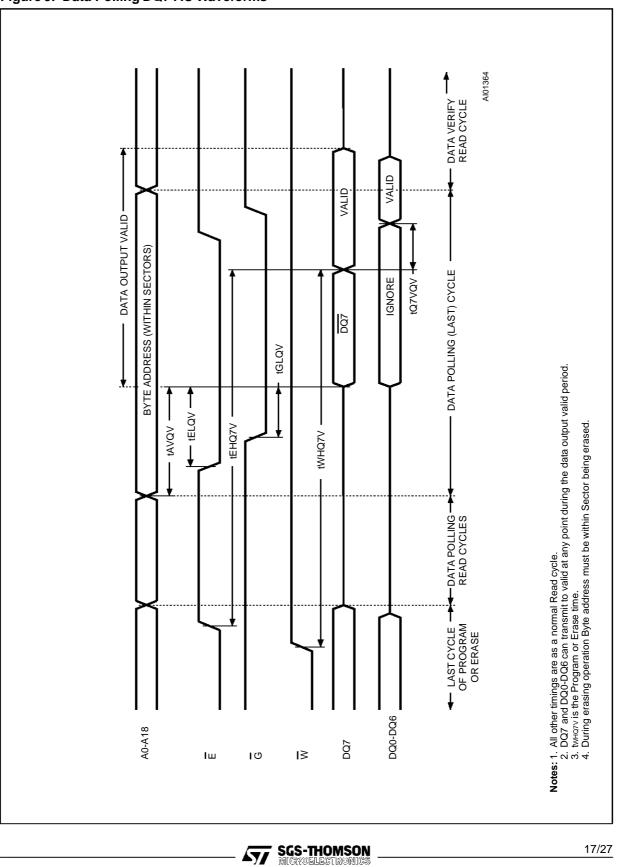


Figure 9. Data Polling DQ7 AC Waveforms

M29V040

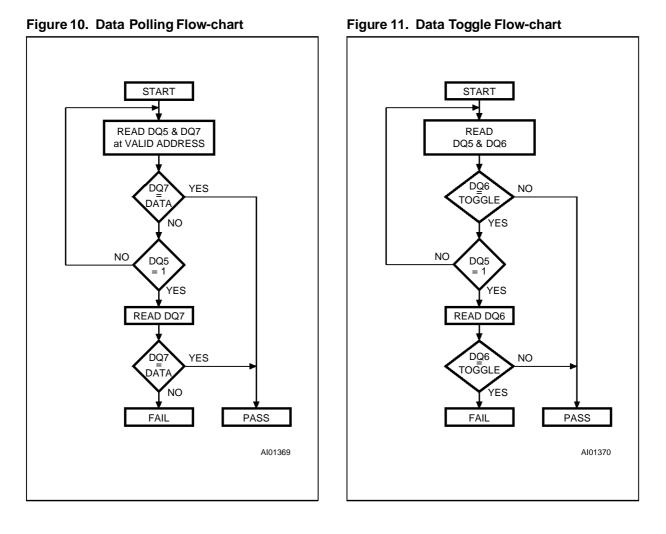


Table 16. Program, Erase Times and Program, Erase Endurance Cycles (T_A = 0 to 70°C; V_{CC} = 3.3V \pm 0.3V)

Parameter		Unit		
i arameter	Min	Тур	Max	
Chip Program (Byte)		8		sec
Bulk Erase (Preprogrammed)		3	30	sec
Bulk Erase		10		sec
Sector Erase (Preprogrammed)		1	30	sec
Sector Erase		2		sec
Byte Program	10		1200	μs
Program/Erase Cycles (per Sector)	100,000			cycles



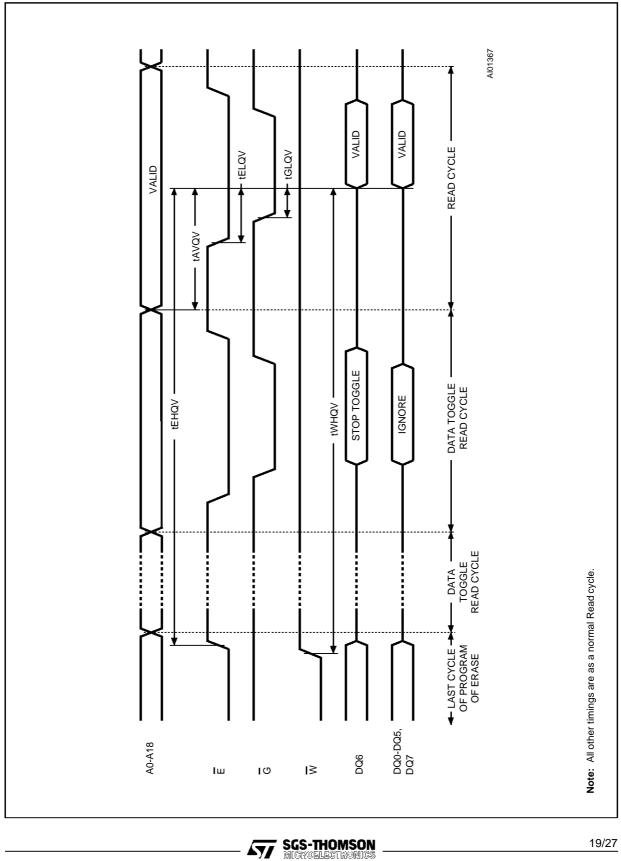


Figure 12. Data Toggle DQ6 AC Waveforms

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Erase Suspend (ES) instruction. The Sector Erase operation may be suspended by this instruction which consists of writing the command 0B0h without any specific address code. No coded cycles are required. It allows reading of data from another sector while erase is in progress. Erase suspend is accepted only during the Sector Erase instruction execution and defaults to read array mode. Writing this command during Erase timeout will, in addition to suspending the erase, terminate the timeout. The Togale Bit DQ6 stops togaling when the P/E.C. is suspended. Toggle Bit status must be monitored at an address out of the sector being erased. Toggle Bit will stop toggling between 0.1µs and 15us after the Erase Suspend (ES) command has been written. The M29V040 will then automatically set to Read Memory Array mode. When erase is suspended, Read from sectors being erased will output invalid data, Read from sector not being erased is valid. During the suspension the memory will respond only to Erase Resume (ER) and Reset (RST) instructions. RST command will definitively abort erasure and result in the invalid data in the sectors being erased.

Erase Resume (ER) instruction. If an Erase Suspend instruction was previously executed, the erase operation may be resumed by giving the command 30h, at any address, and without any coded cycles.

Programing. The memory can be programmed byte-by-byte. The program sequence is started by the two coded cycles, followed by writing the Program command (0A0h) to the Command Interface. This is followed by writing the address and data byte to the memory. The Program/Erase Controller automatically starts and performs the programming after the fourth write operation. During programming the memory status is checked by reading the status bits DQ5, DQ6 and DQ7 which show the status of the P/E.C. DQ6 and DQ7 determine if programming is on going or has completed and DQ5 allows a check to be made for any possible error.

Power Up

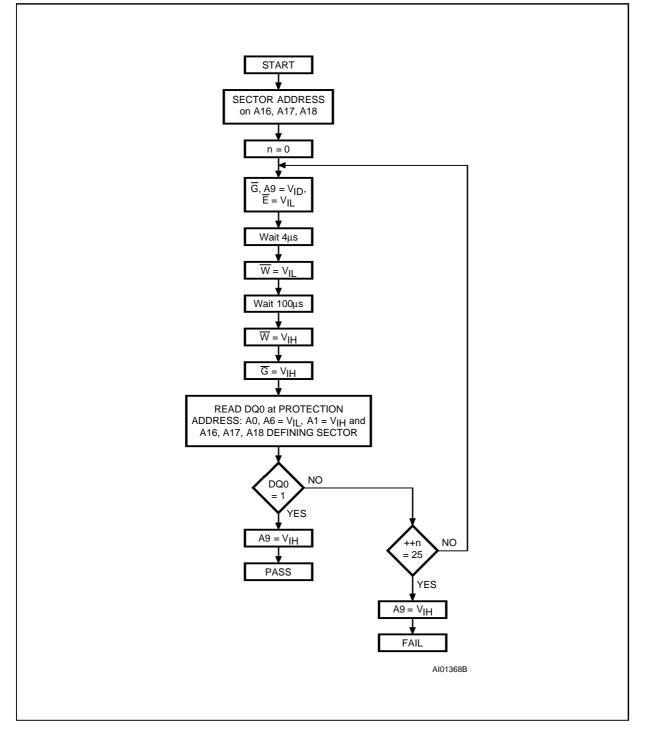
The memory Command Interface is reset on power up to Read Array. Either \overline{E} or \overline{W} must be tied to V_{IH} during Power-up to allow maximum security and the possibility to write a command on the first rising adge of \overline{E} or \overline{W} . Any write cycle initiation is blocked when V_{CC} is below V_{LKO}.

Supply Rails

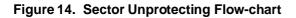
Normal precautions must be taken for supply voltage decoupling, each device in a system should have the V_{CC} rail decoupled with a $0.1\mu F$ capacitor close to the V_{CC} and V_{SS} pins. The PCB trace widths should be sufficient to carry the V_{CC} program and erase currents required.

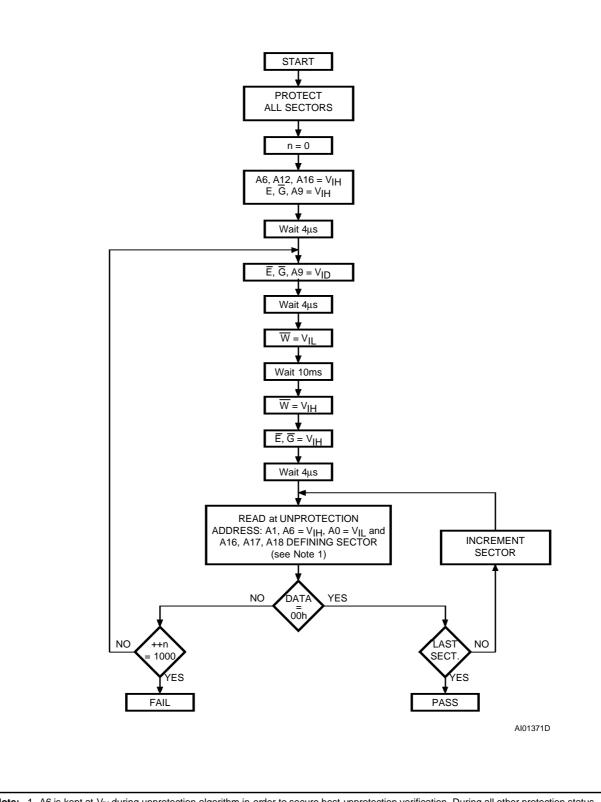








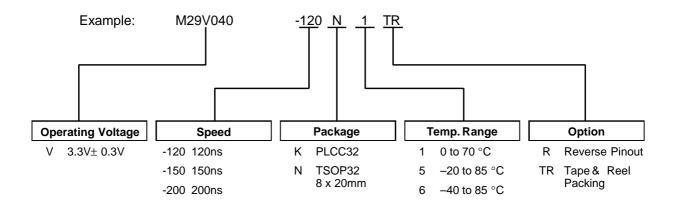




Note: 1. A6 is kept at V_{IH} during unprotection algorithm in order to secure best unprotection verification. During all other protection status reads, A6 must be kept at V_{IL}.



ORDERING INFORMATION SCHEME



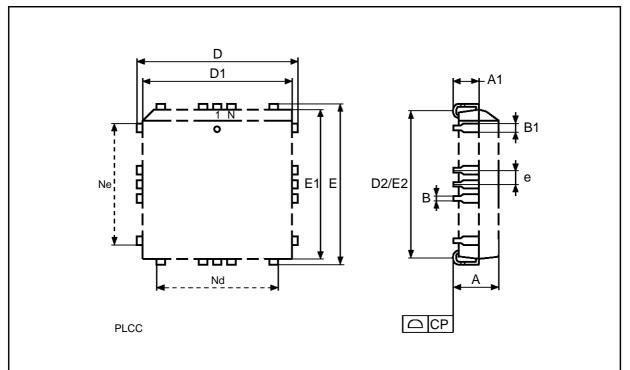
For a list of available options (V_{CC} Range, Speed, etc...) refer to the current Memory Shortform catalogue. For further information on any aspect of this device, please contact the SGS-THOMSON Sales Office nearest to you.

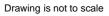


Symb		mm		inches			
Cynib	Тур	Min	Max	Тур	Min	Мах	
А		2.54	3.56		0.100	0.140	
A1		1.52	2.41		0.060	0.095	
В		0.33	0.53		0.013	0.021	
B1		0.66	0.81		0.026	0.032	
D		12.32	12.57		0.485	0.495	
D1		11.35	11.56		0.447	0.455	
D2		9.91	10.92		0.390	0.430	
E		14.86	15.11		0.585	0.595	
E1		13.89	14.10		0.547	0.555	
E2		12.45	13.46		0.490	0.530	
е	1.27	-	-	0.050	-	-	
N	32			32			
Nd		7			7		
Ne		9			9		
СР			0.10			0.004	

PLCC32 - 32 lead Plastic Leaded Chip Carrier, rectangular

PLCC32



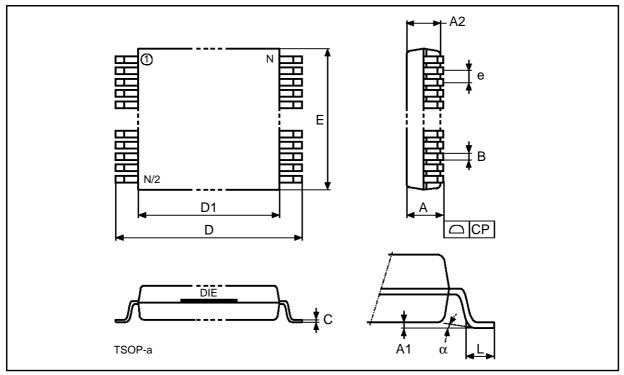




		mm		inches			
Symb	Тур	Min	Max	Тур	Min	Max	
А			1.20			0.047	
A1		0.05	0.17		0.002	0.006	
A2		0.95	1.50		0.037	0.059	
В		0.15	0.27		0.006	0.011	
С		0.10	0.21		0.004	0.008	
D		19.80	20.20		0.780	0.795	
D1		18.30	18.50		0.720	0.728	
E		7.90	8.10		0.311	0.319	
е	0.50	-	-	0.020	-	-	
L		0.50	0.70		0.020	0.028	
α		0°	5°		0°	5°	
N		32			32		
СР			0.10			0.004	

TSOP32 Normal Pinout - 32 lead Plastic Thin Small Outline, 8 x 20mm

TSOP32



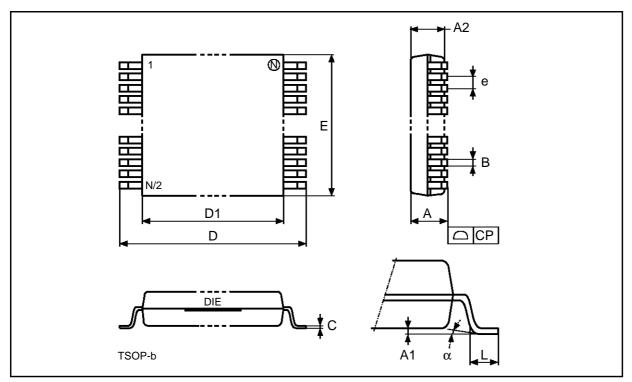
Drawing is not to scale



Symb		mm	_		inches	
cjc	Тур	Min	Мах	Тур	Min	Max
А			1.20			0.047
A1		0.05	0.17		0.002	0.006
A2		0.95	1.50		0.037	0.059
В		0.15	0.27		0.006	0.011
С		0.10	0.21		0.004	0.008
D		19.80	20.20		0.780	0.795
D1		18.30	18.50		0.720	0.728
E		7.90	8.10		0.311	0.319
е	0.50	-	-	0.020	-	-
L		0.50	0.70		0.020	0.028
α		0°	5°		0°	5°
N		32	·		32	

TSOP32 Reverse Pinout - 32 lead Plastic Thin Small Outline, 8 x 20mm

TSOP32



Drawing is not to scale



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